









Hierarchies relating Topology and Geometry

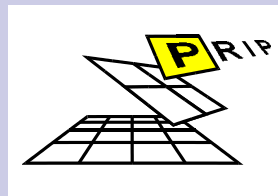
Walter G. Kropatsch, Yll Haxhimusa, Adrian Ion

PRIP (183/2)

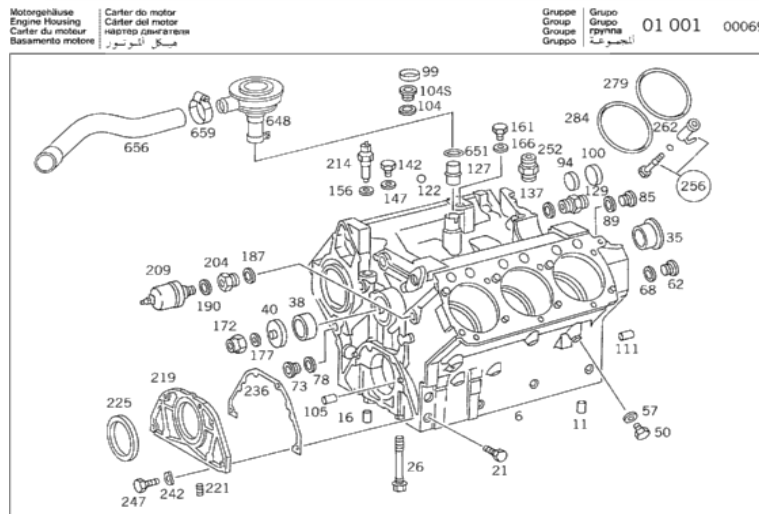
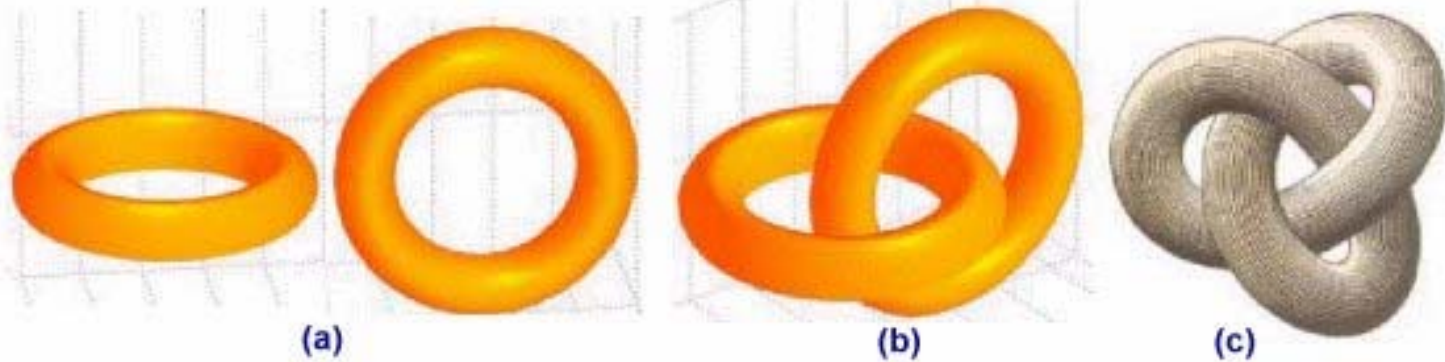
Pattern Recognition and Image Processing

Institute of Computer Aided Automation

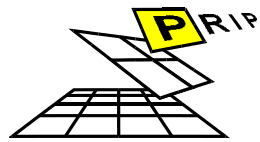
Vienna Univ. of Technology- Austria



Graphs in Image Analysis



- Dual Graph Contraction
- Graph Pyramids

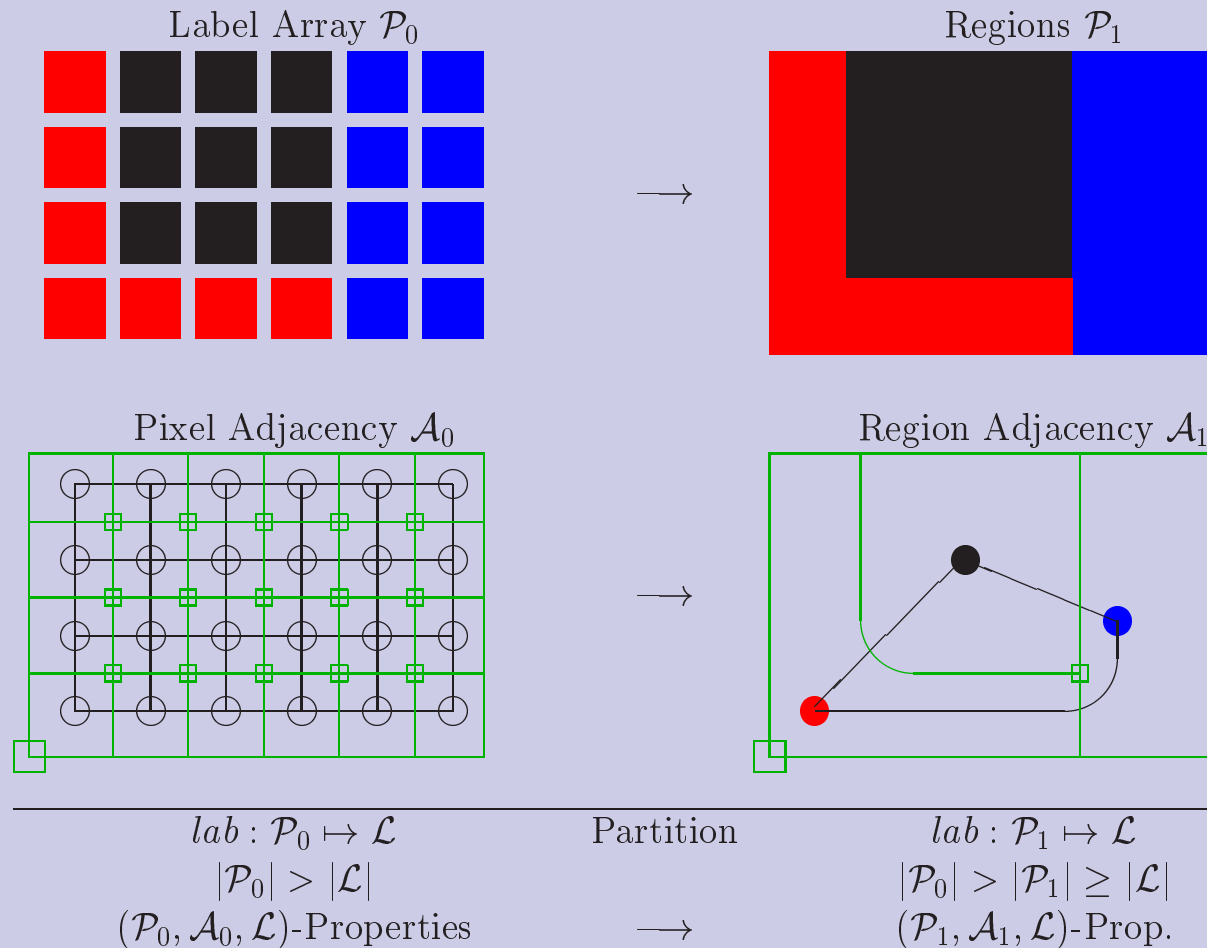


CONTENTS

- The Problem
 - Partitions and Adjacencies
 - How to Reduce the Descriptions
 - Topology Preserving Operations
 - Combinatorial Maps
 - Abstract Cellular Complexes (ACC)
 - Conclusions, Discussion
-

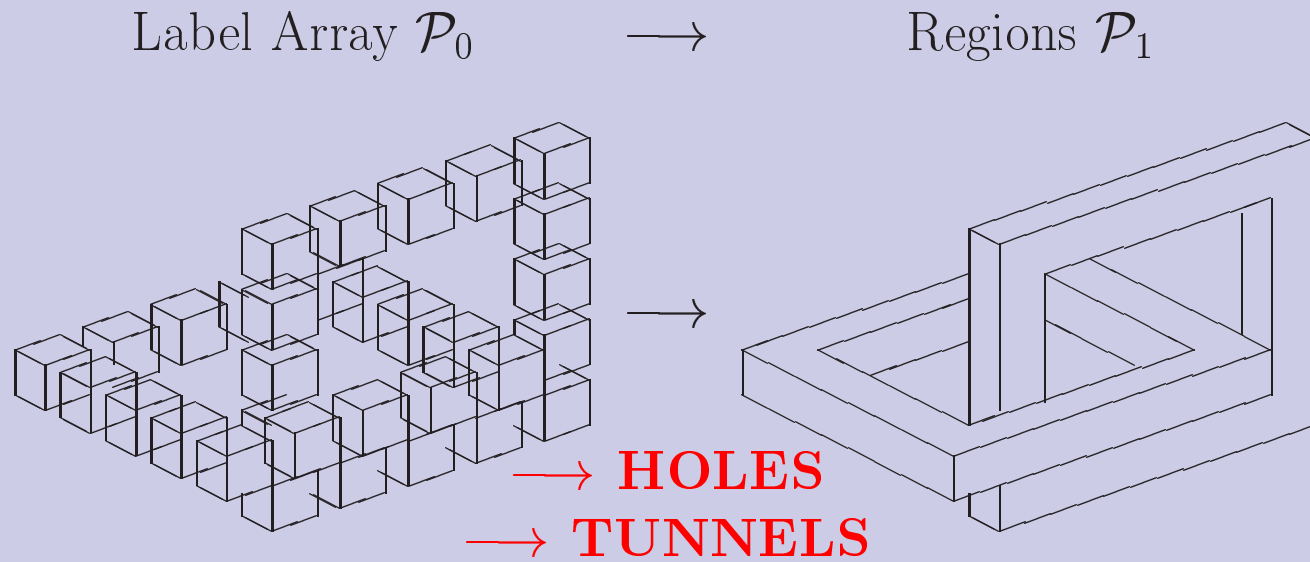
The PROBLEM

in 2D



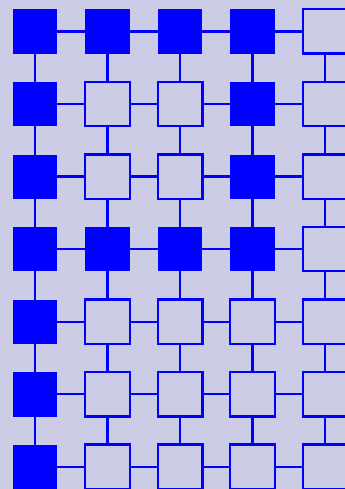
The PROBLEM

in 3D

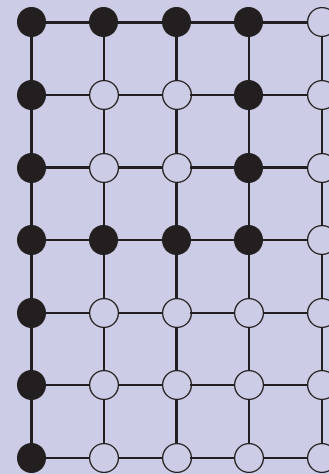


From Pixels To Graphs

IMAGE PIXELS



NEIGHBORHOOD GRAPH

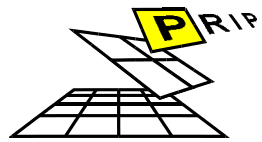


Properties/Relations between $(\mathcal{P}_0, \mathcal{A}_0)$ and $(\mathcal{P}_1, \mathcal{A}_1)$

\mathcal{P}_0	partition 1 Label/Cell	\mathcal{P}_1	partition (?) 1 Cell/Label
$c \in \mathcal{P}_0$	unit square simply connected simplex no inclusion 1 Label/CC ?	$c \in \mathcal{P}_1$	arbitrary shape (simply) connected simplex ? inclusion (tree) $ CC = \mathcal{P}_1 $ minimal
\mathcal{A}_0	4-connected ? well composed embedding Genus(CC(label)) orientation	\mathcal{A}_1	RAG (connected ?) connectivity preserved embedding Genus(CC(label)) orientation artefacts?
$(c_1, c_2) \in \mathcal{A}_0$	$lab(c_1) \neq lab(c_2)$ $lab(c_1) = lab(c_2)$ image edge Jordan boundaries	$(c_1, c_2) \in \mathcal{A}_1$	multiple (lab_1, lab_2) (lab_1, lab_1) (pseudo,self-loop) connected segment Jordan boundaries

How to perform $T : (\mathcal{P}_0, \mathcal{A}_0) \mapsto (\mathcal{P}_1, \mathcal{A}_1)$?

$(\mathcal{P}_0, \mathcal{A}_0)$	$(\mathcal{P}_1, \mathcal{A}_1)$
Pixelarray: $I(x, y)$	Combinatorial 2-Maps $(\mathcal{D}_1, \alpha_1, \sigma_1) + \text{Incl. Tree}$
ACC	Abstract Cellular Complex-graph? G-Maps + Incl. Tree $(\mathcal{D}_1, \alpha_0, \alpha_1, \alpha_2)$
Dual Graphs: $((V_0, E_0), (F_0, \overline{E_0}))$	Dual Graphs $((V_1, E_1), (F_1, \overline{E_1}))$
2-Maps $(\mathcal{D}_0, \alpha_0, \sigma_0)$	$(\mathcal{D}_1, \alpha_1, \sigma_1)$



Possible Realizations of T :

1. direct construction

- (a) Connected Component Labeling
- (b) 2-Maps by Pixelscan
- (c) 2-Maps by Precode-Guided FUSION
- (d) G-Maps by Precode-Guided FUSION?

2. DS conversion + repeated reductions

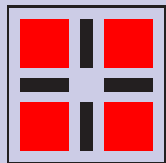
- (a) 2-Maps by Precode-Guided (sequential) FUSION
- (b) Dual Graphs by Parallel Dual Contractions

2D Removal and Contraction

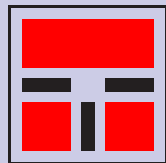
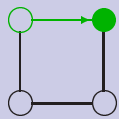
Configuration	Primal Graph	Dual Graph
	Remove	Contract
	merges <i>A</i> and <i>B</i>	

$\text{Common}(A, B) \text{ true} \iff$ Same Label \longrightarrow CCL
 Similar Color \longrightarrow Segmentation
 'belong together' \longrightarrow Grouping

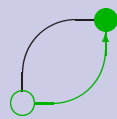
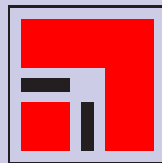
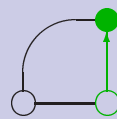
2 × 2 CCL



contract

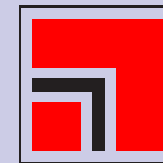
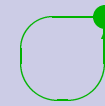
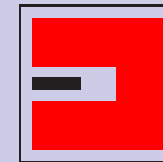


contract



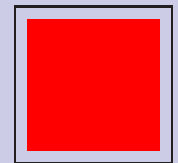
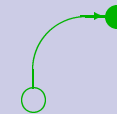
contract

remove



remove

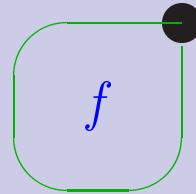
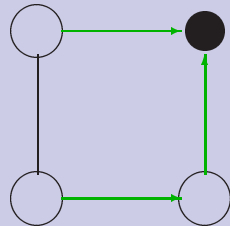
contract



Contraction Kernel, Simplification

contract **more**

simplified



contraction **kernel**

self-loop

removed

Spanning tree

$\deg(f) < 3$

Irregular Graph Pyramid

Building Algorithm

Dual Graph Pyramid Algorithm

Input: Graphs $(G_0, \overline{G_0})$

- 1: **while** further abstraction is possible **do**
- 2: select contraction kernels
- 3: perform graph contraction and simplification of dual graph
 (DGC [Kropatsch, 1995a])
- 4: apply reduction functions to compute new reduced level
- 5: **end while**

Output: Graph pyramid – $(G_k, \overline{G_k}), 0 \leq k \leq h$.

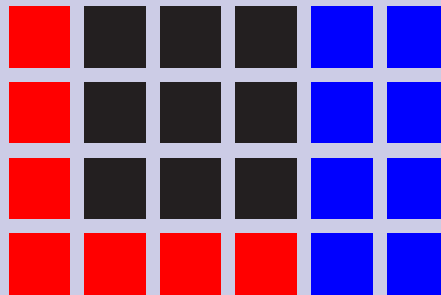
- Graph pyramid is a stack of $(G_k, \overline{G_k}), 0 \leq k \leq h$



Dual Graph Contraction

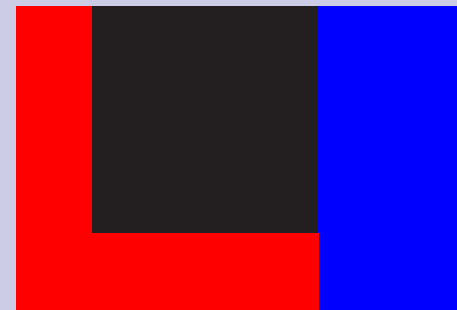
Example 1

Label Array \mathcal{P}_0



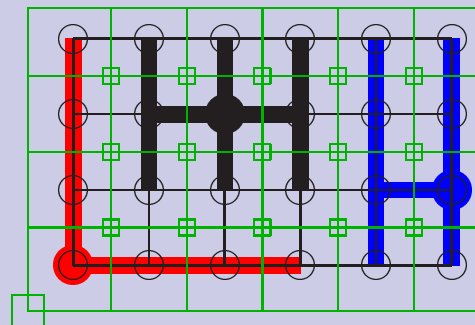
→

Regions \mathcal{P}_1



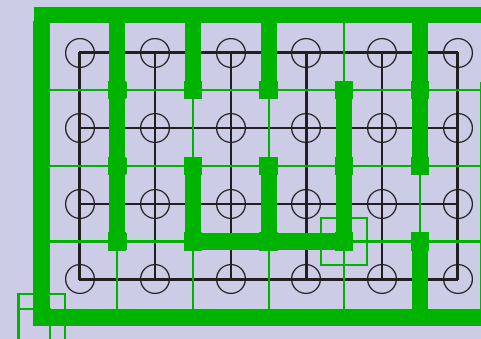
→

Contraction Kernels



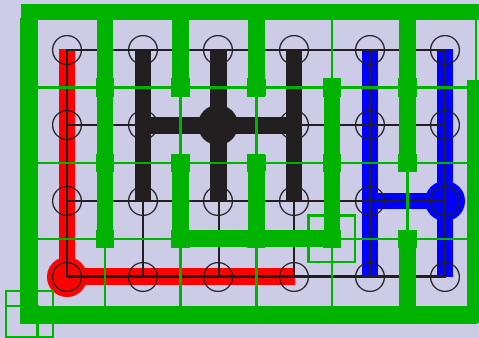
(dual) Simplification Kernels

→

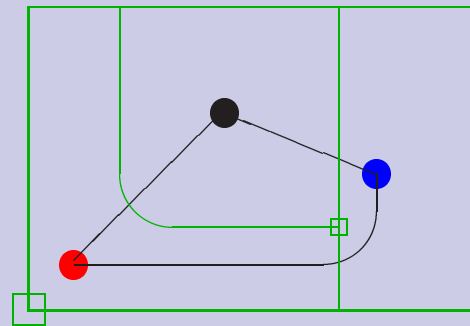


What Remains...

Both Contraction Trees



Contraction Result



local characterization

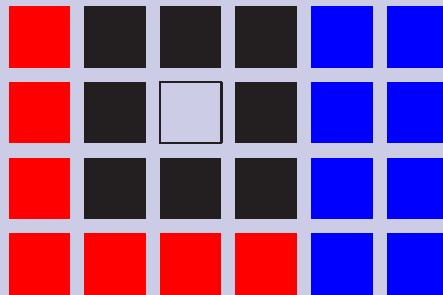


1 cell/CC(label)
 $lab(c_1) \neq lab(c_2)$
 ≥ 3 regions meet
 or background
 removal/**contraction**

Dual Graph Contraction

Example 2

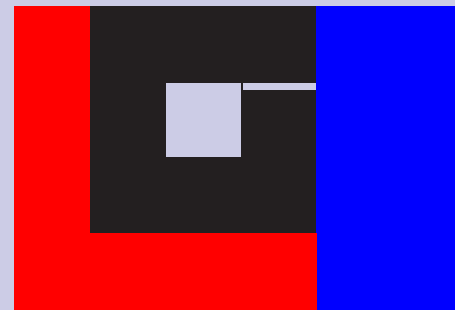
Label Array \mathcal{P}_0



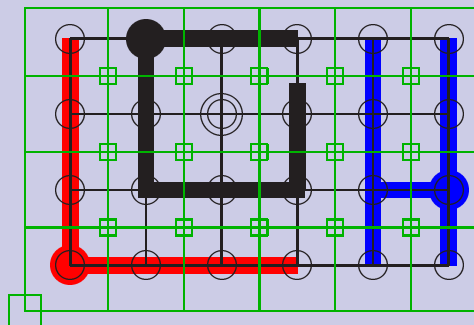
→

Regions \mathcal{P}_1

→

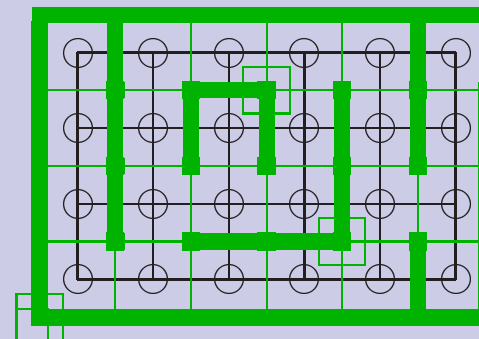


Contraction Kernels



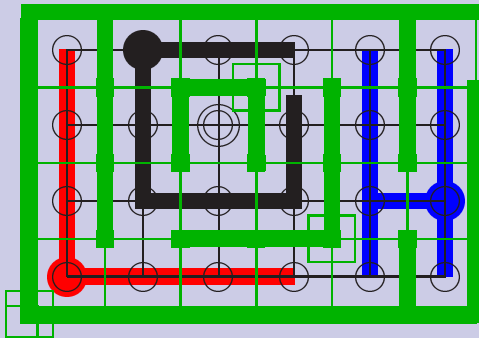
(dual) Simplification Kernels

→

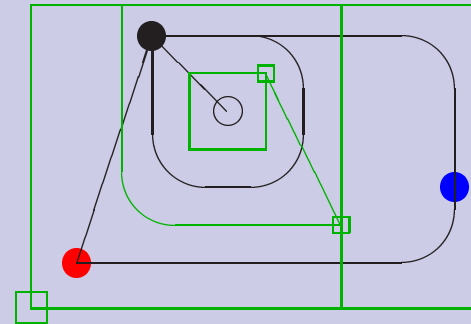


What Remains...

Both Contraction Trees



Contraction Result



local characterization



except



1 cell/CC(label)

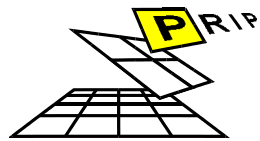
$lab(c_1) \neq lab(c_2)$

self-loop, multi-edge with inclusion

≥ 3 regions meet

or background

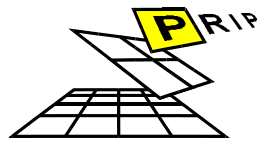
removal/**contraction**



Topology Preserving Operations

in 2D

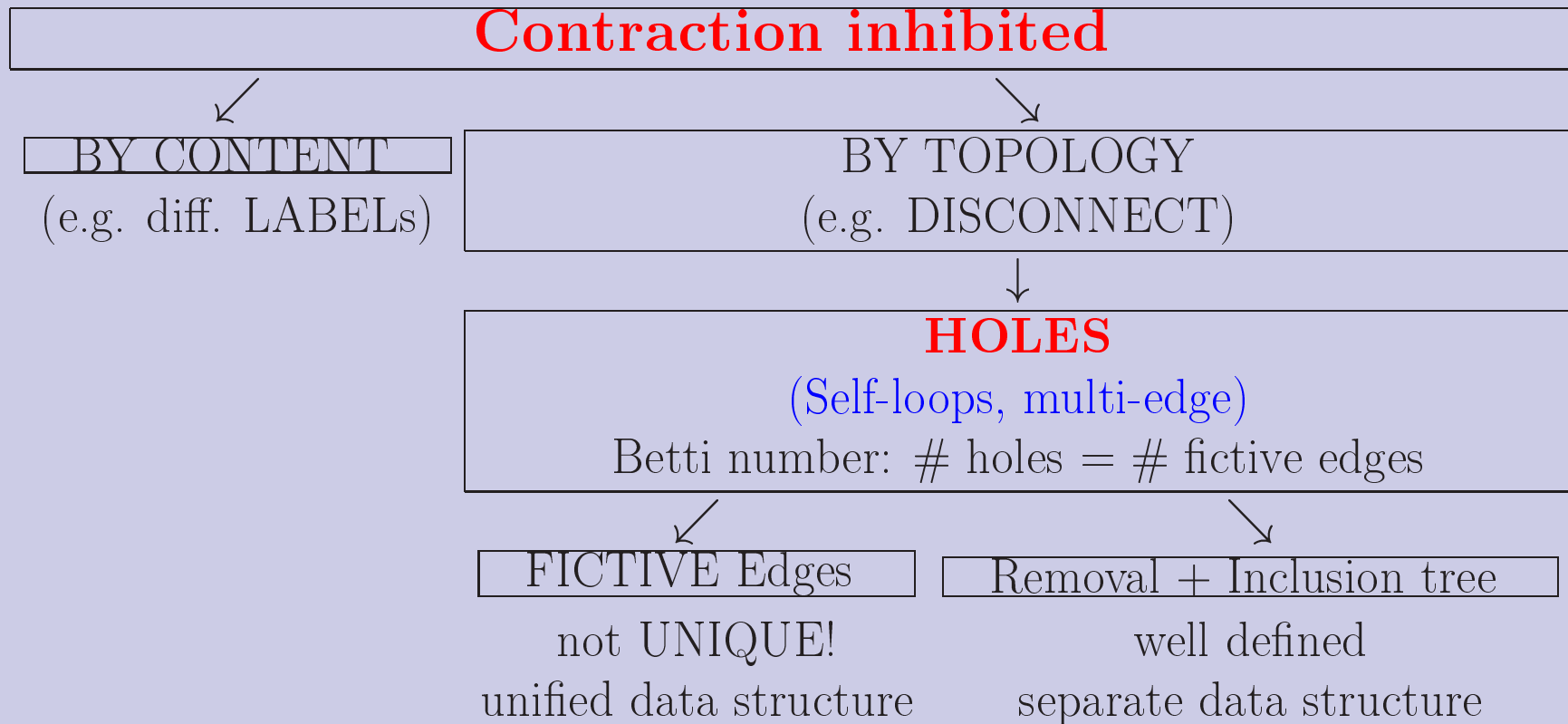
	Points	Lines	Faces	Cond.	PRE-CONDITION
Euler	$\# P$	$-\# L$	$+\# F$	$= \text{const.}$	to preserve:
Incr.	ΔP	$-\Delta L$	$+\Delta F$	$= 0$	Euler; Orientation
Contract(l, p_0)	-1	-1		(p_1, l, p_0)	$p_1 \neq p_0$;
Remove(l, f_0)		-1	-1	(f_x, l, f_0)	$(f_x \neq f_0)$; $\text{deg}(f_0) \leq 2$
Any Incr.	$(-a$	$-b$	$-c)$		$b = a + c$;
by a contr.	$(-1$	$-1)$		$\times a$	
by c remov.		$(-1$	$-1)$	$\times c$	



A Few Comments

1. $p_0 \neq p_1 \implies$ no contraction of self-loop.
2. (f_x, l, f_0) : self-loop in dual = bridge in primal, Removal \implies Disconnection.
3. removal: l not bridge, since $(f_x, l, f_0 \neq f_x)$ not self-loop \implies removal does NOT disconnect.
4. $\deg(f_0) > 2 : (f_x, l, f_0, l_i), i = 1, 2, \dots$: order of (f_x, l_i) may change.
5. Contraction and removal are the ONLY operations needed.
6. Any other topology-preserving operation can be achieved by appropriate combinations of contraction and removals.
7. Note that negative contractions and negative removals are possible as the inverse operations under certain pre-conditions.
8. Pre-conditions for individual operations can be extended to sets of operations: FOREST requirement (no cycle) for contraction.
9. CC: additional pre-condition: $lab(p_1) \neq lab(p_2)$.

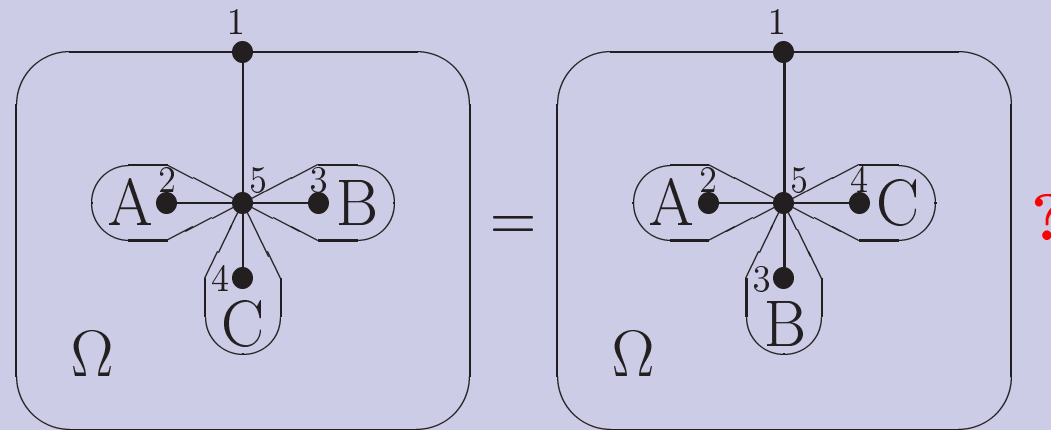
What remains after repetition?



Dual Graphs

vs.

Maps



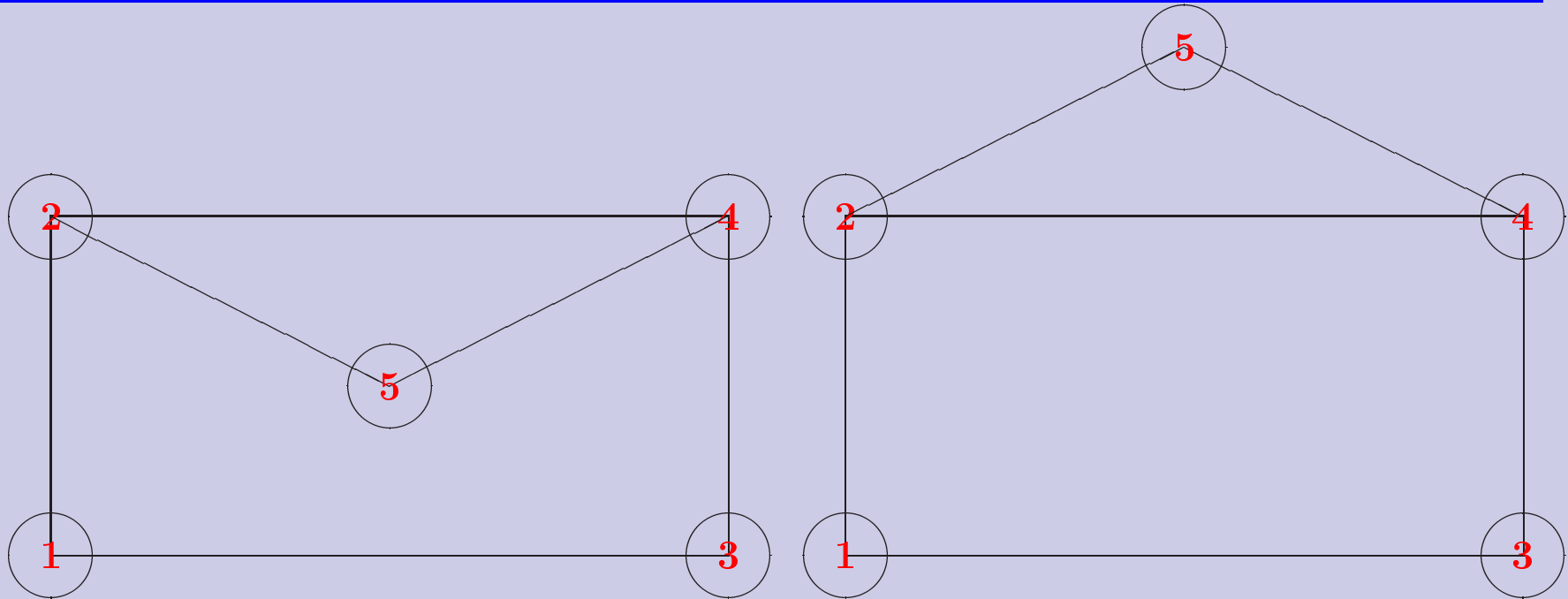
Dual Graphs CANNOT distinguish,

MAPS can!

Reason: self-loops lose local orientation:

- $(1, 1; \Omega, \infty),$
- $(1, 5; \Omega, \Omega),$
- $(5, 5; A, \Omega),$
- $(5, 2; A, A),$
- $(5, 5; C, \Omega),$
- $(5, 4; C, C),$
- $(5, 5; B, \Omega),$
- $(5, 3; B, B)\}$

Envelope: Graph



Adjacency Matrix:

	1	2	3	4	5
1		1	1		
2	1			1	1
3	1			1	
4		1	1		1
5		1		1	

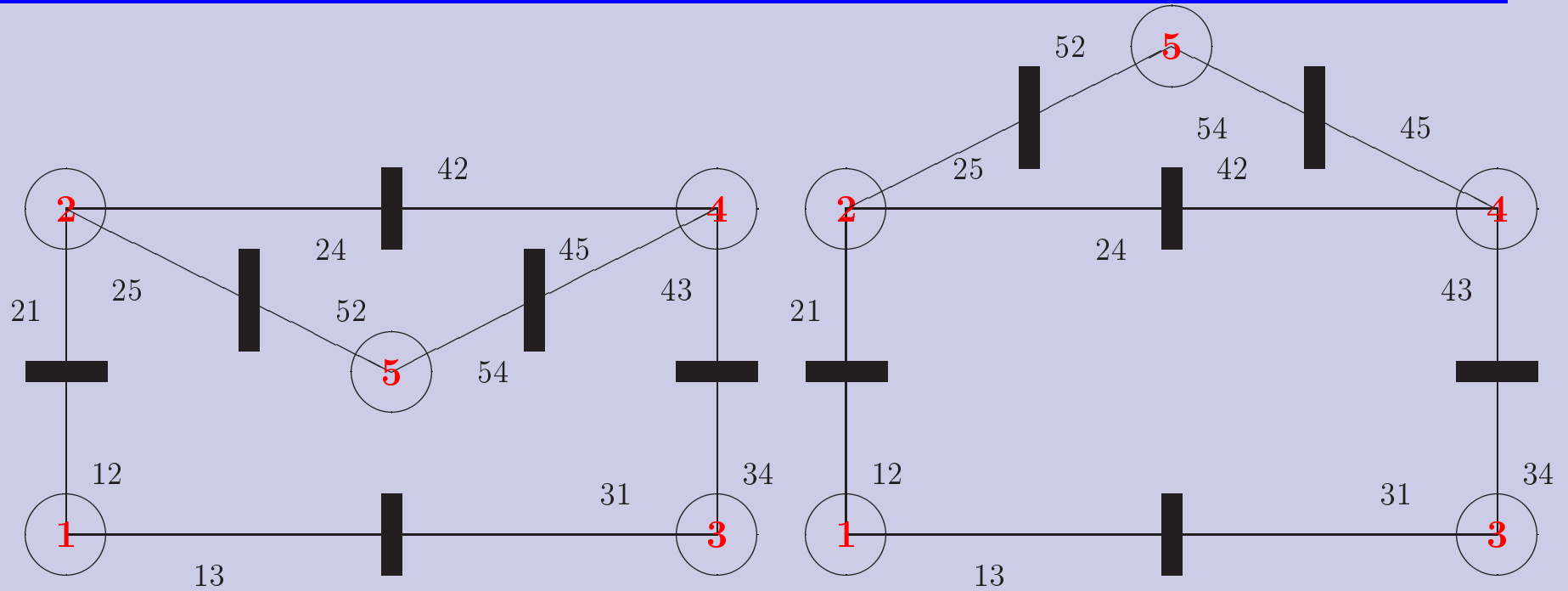
Adjacency Matrix:

	1	2	3	4	5
1		1	1		
2	1			1	1
3	1			1	
4		1	1		1
5		1		1	

next:

Envelope: Combinatorial Map $(\mathcal{D}, \sigma, \alpha)$

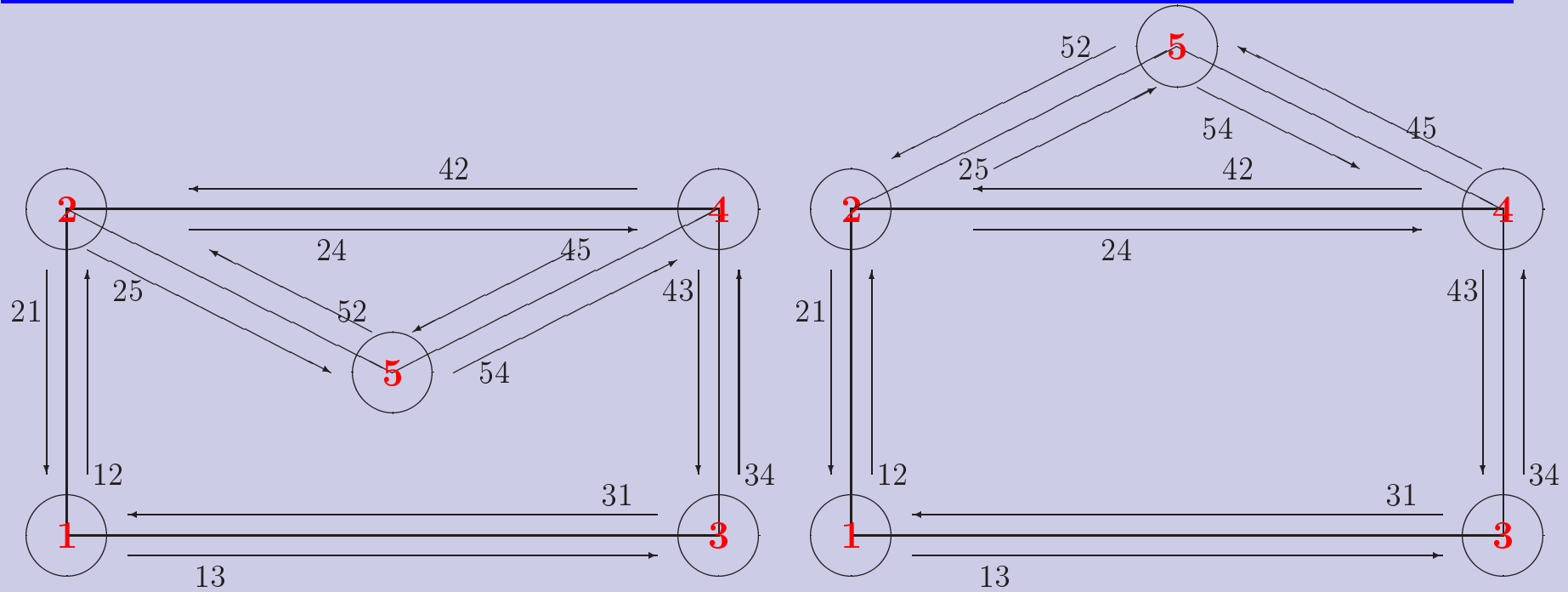
Envelope: Combinatorial Map $(\mathcal{D}, \sigma, \alpha)$



\mathcal{D}	12	13	21	24	25	31	34	42	43	45	52	54
α	21	31	12	42	52	13	43	24	34	54	25	45
σ	13	12	25	21	24	34	31	45	42	43	54	52

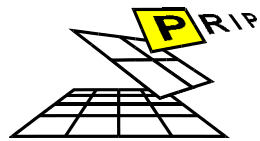
\mathcal{D}	12	13	21	24	25	31	34	42	43	45	52	54
α	21	31	12	42	52	13	43	24	34	54	25	45
σ	13	12	24	25	21	34	31	43	45	42	54	52

Envelope: Combinatorial Map $(\mathcal{D}, \beta_1, \beta_2)$



\mathcal{D}	12	13	21	24	25	31	34	42	43	45	52	54
β_2	21	31	12	42	52	13	43	24	34	54	25	45
β_1	13	12	25	21	24	34	31	45	42	43	54	52

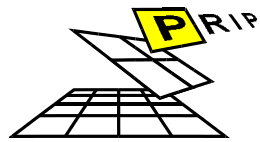
\mathcal{D}	12	13	21	24	25	31	34	42	43	45	52	54
β_2	21	31	12	42	52	13	43	24	34	54	25	45
β_1	13	12	24	25	21	34	31	43	45	42	54	52



Topology Preserving Operations

in 3D

	Pts	Lin.	Fac.	Vol.	Cond.	PRE-CONDITION
Euler	$\# P$	$-\# L$	$+\# F$	$-\# V$	$= \text{const.}$	
Incr.	ΔP	$-\Delta L$	$+\Delta F$	$-\Delta V$	$= 0$	pres.Euler
V-Fusion			-1	-1	(v_1, f, v_2)	$v_1 \neq v_2?$ (deg $f = 2$)
F-Fusion		-1	-1		(f_1, l, f_2)	$f_1 \neq f_2?$ deg $l \leq 2$
L-Fusion	-1	-1			(l_1, p, l_2)	$l_1 \neq l_2?$ deg $p \leq 2$
Any Incr.	$(-a$	$-b$	$-c$	$-d)$	pres.Euler	see below
by V-Fus.			$(-1$	$-1)$	$\times d$	
by F-Fus.		$(-1$	$-1)$		$\times (c - d)$	
by L-Fus.	$(-1$	$-1)$			$\times a$	with $b + c = a + d$



A Few Comments

1. V-Fusion, F-Fusion and L-Fusion are **the ONLY operations** needed.
2. Any other topology-preserving operation can be achieved by appropriate **combinations**.
3. Pre-conditions for individual operations can be extended to sets of operations: FOREST requirement (**NOTHING INSIDE**) and ??.
4. Note that negative Fusions are possible under certain pre-conditions as the **inverse operations**.
5. Pre-conditions 2 in 3D are **not trivial** except for faces: a line may delimit more than 2 faces, and a point may be the intersection of more than 2 lines.
6. Note that the **L-fusion in 3D** eliminates a point along a line sequence whereas the **contraction in 2D** eliminates a line between two points. As result the 2D contraction produces a point while 3D l-fusion produces a line.
7. **CC**: additional pre-condition: $lab(v_1) \neq lab(v_2)$, no further pre-condition for F-Fusion and L-Fusion.

What remains after repetition?

Contraction inhibited

BY CONTENT
(e.g. diff. LABELS)

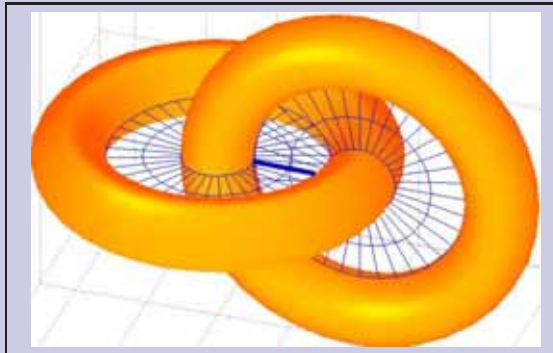
BY TOPOLOGY
(e.g. DISCONNECT)

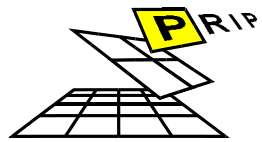
TUNNELS

HOLES

FICTIVE Elements

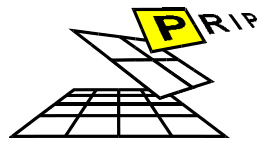
Removal + Inclusion tree





Some useful properties:

1. we need **multi-edge and self-loop**
2. combine operations (like ECK)
3. repeated contraction, termination criteria
4. pseudo/fictive elements characterize topological relations
pseudo edge \longleftrightarrow hole, pseudo face \longleftrightarrow tunnel, ...
5. independence of operations allows for:
 - parallelism
 - optimized scan
 - divide and conquer



Open problems:

1. 3D, 4D
2. interlaced thori
3. Re-insertion of removed edges/darts (a la wavelet)
4. pre-condition (single OP) \implies pre-condition (set of OPs)
5. repeated contraction:
 - different selection criteria
 - different termination criteria
 - different attributes
 - different reduction functions
6. Betti numbers? homology groups? generators?
7. appropriate applications?

Thank you